

Adding ASR to an Akraino Robot

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Prepared by Signalogic for Akraino Technical Meeting 1Q22

Contents

Executive Summary

Problems

- cloud computing is not edge computing
- long "supply chain" from cloud to edge

Robot Needs

- deal with environment at the edge
- operate safely don't hurt anyone, don't damage property. Operate with zero trust in cloud commands
- operate with energy and size constraints

• EdgeStream[™] - Software

- optimized on per thread basis, one thread per core, no spinlocks
- packet processing, media codecs, signal processing, inference
- comparison with DeepStream and GStreamer

• EdgeStream[™] - Hardware

- pico ITX form factor: 3.5" x 3.5"
- quad-core Atom, no fan

Deployments

Github and Docker Hub

- Demos, reference apps, ready-to-run containers, example command lines
- Source code

Executive Summary



- key blueprint organizations: Fujitsu and Ritsumeikan University
- Robot compute resources are typically not sufficient for real-time, high accuracy, high vocabulary ASR
- Initial demo is a Roomba
 - quad-core pico ITX board and battery "dead bugged" on a Roomba
 - voice commands are processed and sent to the Roomba's API via USB; e.g. "stop", "come back later", "turn left", etc.

Problems Facing Robotics ASR



Robots are a quintessential edge application

- compute resources and power consumption are strictly limited. There is no "economy of scale"
- operation cannot depend on continuous internet connectivity

Human safety is paramount

 accuracy must be high – when someone says "stop, back up" robots must immediately do exactly that

Edge data is private data

 Images and audio may contain identifying / proprietary information. Audio data cannot be sent to the cloud over a "long supply chain" of zones, regions, services



Source: AWS, 2020

Problems, example



Why talk to your roomba through the cloud ?

- the "centralized cloud" model is based on huge scale, data collection, analytics, command and control, and complexity
- not based on energy and performance efficiency, safety, and data privacy



Robot Needs

Deal with environment at the edge

- respond to voice commands
- vision avoid people, pets, property. Don't break things

Operate safely - don't hurt anyone, don't damage property

- operate with zero trust in cloud commands the measurable physical situation always takes precedence
- actively pursue and detect malware

Share content with other edge nodes

 share private edge data – which will become massive amounts as we go forward

Energy and size constraints

- operate with 50 250 W power consumption, strive for "no fans"
- operate in small-form factor boxes: 1/2 1U, mini-ITX, smaller





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Software – EdgeStream[™] Platform



Input from USB audio or RTP packets

- input from one more microphones

Pre-processing (e.g. background noise removal)

- environment background noise
- robot noise, e.g. motors, wheels, brushes

Application specific processing

- lawful intelligence / interception
- telecom
- ASR

Output commands to connected devices as needed

- translate recognized text to command APIs

EdgeStream Data Flow



Per core data flow

- one thread per core
- no spinlocks
- precise control over power consumption

Real-time workflow

- packet handling
- media codecs
- signal processing
- user-defined processing
- inference

Hardware acceleration

- DirectCore® option
- x86 and Arm options supported



EdgeStream Workflow



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Comparison with DeepStream

EdgeStream[™] DeepStream Functional Mapping

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- Packet Processing
 - EdgeStream provides telecom grade packet processing, including...
 - loss repair
 - 500+ out-of-order handling
 - support for encapsulated protocols
 - multiple RFCs
 - logging

Media •

- includes encoders in addition to decoders
- Signal processing
 - more user-defined insertion points





Comparison with GStreamer



Thread architecture

- EdgeStream allocates one workflow thread per core ("unified thread")
- GStreamer uses a thread slicing architecture – flexible but requires spinlocks

Packet Processing

- EdgeStream provides telecom grade packet processing, including …
- loss repair
- 500+ out-of-order handling
- supports encapsulated protocols
- multiple RFCs
- logging





Hardware – EdgeStream[™] Platform

Pico ITX form-factor board

- 3.5" x 3.5" form-factor
- quad-core Atom, 10 to 20 W power consumption
- integrated SSD, WiFi, HDMI, etc.
- no fan
- boots Ubuntu 20.04

Essentially a "robot server"

- straightforward to develop code on lab and cloud servers, then run on a robot server
- lab / cloud servers can easily simulate robot servers by controlling number of cores and clock rate
- handles up to three (3) concurrent ASR streams, or three (3) far-field microphones for one stream, or a combination





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EdgeStream Deployments



• Asia

- Japan
- India (ISRO)
- Australia
- New Zealand (OpenLI¹ support)

• Europe

- Germany
- Italy
- Czech Republic

North America

- AFRL
- Raytheon
- Boeing

Github and Docker Hub



• Github

- SigSRF software page: <u>https://github.com/signalogic/SigSRF_SDK</u>
- example command lines for reference apps and demos
- documentation

Docker Hub

- ready-to-run Ubuntu and CentOS containers https://hub.docker.com/u/signalogic

Demos and reference apps

- ready-to-run containers on Docker Hub, installation Rar packages on Github
- help with installing and running demos available over Skype (no charge)

Source code

- developed entirely in US
- no dependencies on 3rd party libraries

Thanks !



- Q&A
- Follow-up questions / comments: info@signalogic.com
- Web page: https://signalogic.com/edgestream

Supplemental

• Following slides are background info ...

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Overview

EdgeStream™ Workflow © Signalogic 2021

Rev 1a, Dec 2021



SigSRF libraries

- codecs
 - VoLTE (EVS, AMR-NB, AMR-WB)
 - legacy (G729, EVRC, GSM, etc)
 - mil/gov (MELPe)
- packet procesing
 - media/SID packet repair (out-of-order, packet loss, RTP timestamps)
 - timing reconstruction of missing/damaged arrival timestamps
 - child streams (RFC8108)
- frame processing
 - "stream groups" can be defined for related streams
 - · per-stream correction for overrun, underrun, gaps, bursts
 - · accurate time-aligned merging / mixing of multiple endpoints
 - high capacity multiple concurrent streams

EdgeStream[™] applications

- reference apps for customer-defined development
- also used as-is by many of our customers. Most common: telecom, LI, and ASR
- key features
 - dynamic session creation
 - packet push/pull API interface with SigSRF libs
 - multiple streams from multiple sources
 - flexible command line similar to ffmpeg or sox



Overview – Pipeline Flow



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Overview – Per Thread Data Flow



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Functionality – Packet Processing

Media quality – packet level

- media/SID packet repair
 - out-of-order (ooo)
 - packet loss
 - RTP timestamps
- child streams (RFC8108)
- timing reconstruction for missing/damaged packet arrival timestamps

Huge levels of ooo handled

 to support TCP encapsulated UDP/RTP, for example lawful interception apps implementing ETSI protocols

Packet logging / tracing

- per stream packet logging
- timestamp reconciliation
- individual packet tracing



Ingress Packet info for SSRC = 0xbad52e64, first seq num = 3, last seq num = 651 \dots

eq	num	4 0	000 3	3	timestar	np	=	1280,	pkt 1	Len =	6	SID
еq	num	3 с	000 4	ł	timestar	np	=	960, <u>p</u>	okt le	en = (51	
eq	num	5			timestar	np	=	3840,	pkt 1	Len =	6	SID
eq	num	6			timestar	np	=	6400,	pkt 1	Len =	6	SID
eq	num	7			timestar	np	=	8960,	pkt]	len =	6	SID
eq	num	8			timestar	np :	=	11520,	pkt	len =	= 6	5 SID
eq	num	9			timestar	np :	= :	14080,	pkt	len =	= 6	5 SID
eq	num	10			timesta	amp	=	16640), pkt	: len	=	6 SID
eq	num	12	000	11	timesta	amp	=	18560), pkt	: len	=	61
eq	num	15	000	12	timesta	amp	=	19520), pkt	: len	=	61
eq	num	11	000	13	timesta	amp	=	18240), pkt	: len	=	61
eq	num	13	000	14	timesta	amp	=	18880), pkt	: len	=	61
eq	num	14	000	15	timesta	amp	=	19200), pkt	: len	=	61
eq	num	18	000	16	timesta	amp	=	20480), pkt	: len	=	61
eq	num	19	000	17	timesta	amp	=	20800), pkt	: len	=	61
eα	num	16	000	18	timesta	amp	=	1984(), pkt	: len	=	61
eq	num	21	000	19	timesta	amp	=	21440), pkt	: len	=	6 SID
eα	num	23	000	20	timesta	amp	=	23680), pkt	: len	=	61
eq	num	24	000	21	timesta	amp	=	24000), pkt	: len	=	61
eα	num	25	000	22	timesta	amp	=	24320), pkt	: len	=	61
eα	num	27	000	23	timesta	amp	=	24960), pkt	len	=	61
- a	num	28	000	2.4	timesta	amp	=	25280), pkt	len	=	61
ea	num	31	000	25	timesta	amp	=	26240), pkt	: len	=	61
-0	num	32	000	26	timesta	amp	=	26560), pkt	len	=	61
-0	num	34	000	27	timesta	amp	=	27200), pkt	len	=	61
-0	num	17	000	2.8	timesta	amp	=	20160), pkt	len	=	61
-0	num	20	000	29	timesta	amp	=	21120), pkt	len	=	61
-0	num	22	000	30	timesta	amp	=	23360), pkt	len	=	61
	n 11m	26	000	31	timesta	amp	=	24640), pkt	len	=	61
29	num	29	000	32	timesta	amp	=	25600), pkt	len	=	61
	n.11m	30	000	33	timesta	amp	=	25920), pkt	len	=	61
-9	num	33	000	34	timesta	amp	_	26880	$r_{\rm pkt}$	len	_	61
29	num	35	000	01	timeeta	amp	_	27520) pkt	- 1en	_	61
-4	num	37	000	36	timeet:	amp	_	28160	p_{nkt}	- 100	_	61
29	num	38	0000	37	timeeta	amp	_	28480) pkt	- 1en	_	61
-4	num	40	000	38	timeet:	amp	_	20120	p_{nkt}	- 100	_	61
-4	num	42	000	39	timeet:	amp	_	29760	$r_{p, p, r_{r}}$	- len	_	61
-4	num	44	000	40	timeeta	amp	_	30400	p_{nkt}	- 1en	_	61
-9	num	46	000	41	timeet:	amp	_	31 0 4 0	p_{nkt}	- len	_	61
-4	num	36	000	42	timeeta	amp	_	27840	p_{nkt}	- 1en	_	61
-4	num	10	000	42	timeste	mp	_	21601) pict	lon	_	61
=4 20	num	30	000	4.5	timesta	amp		20000	r_{p}	lon		61
-4	num	41	000	45	timesta	amp	_	29440	r_{μ} problem	- 1en	_	61
-4	num	50	000	46	timest	amp	_	22320	r, pri	- 10n	_	61
-4	num	53	000	47	timest	amp	_	33201) pki	- len	_	61
-4	num	55	000	10	timost	-mp	_	33020) pki	lon	_	61
=4	num	13	000	40	timosta	quip	_	30000), prot	. len	_	61
=4	num	40	000	4 <i>2</i>	timesta	anip	_	30000), pru	. ien	_	61
≠q	num	57	000	50	cimesta	amp	=	34360	, prt	. ⊥en	=	υ⊥

Packet Log Excerpt

Ingress Packet info for SSRC = 0xbad52e64, first seq num = 3, last seq num = 651 ...

Seq num 4 ooo 3	timestamp = 1280, pkt len = 6 SID
Seg num 3 000 4	timestamp = 960, pkt len = 61
Seq num 5	timestamp = 3840 , pkt len = 6 SID
Seq num 6	timestamp = 6400, pkt len = 6 SID
Seq num 7	timestamp = 8960, pkt len = 6 SID
Seg num 8	timestamp = 11520 , pkt len = 6 SID
Sec num 9	timestamp = 14080 , pkt len = 6 SID
Seg num 10	timestamp = 16640 , pkt len = 6 SID
Seg num 12 000 11	timestamp = 18560, pkt len = 61 High amoun
Seg num 15 000 12	timestamp = 19520 , phi $m = 61$
Seg num 11 000 13	timestame $\dots $ pkt len = 61
Seg num 13 000 14	m = stamp = 18880, pkt len = 61
Seg num 14 000 15	timestamp = 19200 , pkt len = 61
Seg num 18 000 16	timestamp = 20480 , pkt len = 61
Seg num 19 000 17	timestamp = 20800 , pkt lep = 61
Seg num 16 000 18	timestamp = 19840 pit len = 61
Seg num 21 000 19	timestamp = 21440 pkt len = 6 STD
Seg num 23 000 20	timestamp = 23680 pt len = 61
Seq num 24 000 20	timestamp = 24000 , pt len = 61
Seq num 25 000 21	timestamp = 24320 pt len = 61
Seq num 27 000 22	timestamp = 24960 pkt lon = 61
Seq num 28 000 23	timestamp = 23280 , pkt len = 61
Seq num 31 000 24	timestamp = 25240 , pt len = 61
Seq num 32 000 25	timestamp = 26560 pkt len = 61
Seq num 34 000 20	timestamp = 27200 , ptt len = 61
Seq num 17 000 27	timestamp = 27200 , pkt ien = 61
Seq num 20 000 28	timestamp = 20100, pkt lop = 61
Seq num 22 000 29	$t_{\text{inestamp}} = 2120$, pkt $t_{\text{inestamp}} = 61$
Seq num 26 000 30	timestamp = 23500 , pkt len = 61
Seq num 20 000 31	timestamp = 24640 , pkt lop = 61
Seq num 30 000 32	timestamp = 25000 , pkt lon = 61
Seq num 33 000 33	timestamp = 26920 , pkt lon = 61
Seq num 35	timestamp = 27520 pkt len = 61
Seq num 37 coo 36	timestamp = $2/320$, pkt ien = 61
Seq num 39 000 30	timestamp = 23480 , pkt lon = 61
Seq num 40 000 38	timestamp = 20100, ptt len = 61
Seq num 42 000 38	timestamp = 29760 pkt lop = 61
Seq num 44 000 39	timestamp = 30400 , pkt lop = 61
Seq num 46 000 40	timestamp -30400 , pkt lop -61
Seq num 36 000 41	timestamp = 27840 pkt len = 61
Seq num 48 000 42	timestamp = 31680 ptt len = 61
Seq num 39 000 43	timestamp = 28800 pkt len = 61
Seq num 41 000 45	timestamp = 20110 ptt len = 61
Seq num 50 000 45	timestamp = 2320 pt len = 61
Seg num 53 000 40	timestamp = 3220, pkt len = 61
	timestamp = 33920 , pkt len = 61
Seg num 43 000 49	timestamp = 30080 pkt len = 61
Seg num 57 000 49	timestamp = 34560 pkt len = 61
50g man 57 000 30	crucocamb - 21000, byc ren - or

High amount of ooo (out-of-order) example

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Functionality – Frame Processing

Decoded packet audio data

- buffered as frames (see Overview diagrams)
- signal processing
- Media quality frame level
 - "stream groups" can be defined for streams related in some way
 - per-stream correction for overrun, underrun, gaps, bursts
 - accurate time-aligned merging / mixing of multiple endpoints

Real-time output streaming

- some applications require real-time output, either per-stream or merged between related streams, typically in G711 format
- high intelligibility required all streams fully merged (non-overlapped) and nonduplicated as if all endpoints are in the same room

High capacity – multiple concurrent streams



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Real-Time Streaming Output Example



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Functionality – Applications



Dynamic and static session creation

- sessions created and codecs detected on-the-fly using (i) RTP only (ii) SIP invite packets (iii) .sdp files, or pre-set using static session config files
- RTP only uses heuristic codec type detection

Packet push/pull interface to SigSRF libs

- reference application examples
- Packet pull includes transcoded output, real-time streaming output

Event logging

- critical, major, minor, info, debug levels
- includes alerts for thread pre-emption, queue starvation, and other performance / data related conditions
- per-stream stats (i) on-demand, (ii) when streams close

Arrival timestamp reconstruction

- if needed due to missing / damaged arrival timestamps
- algorithms based on queue balancing, decoded frame rate estimation

Event Log Example

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00:00:00.000.011 INFO: DSConfigPktlib() uflags = 0x7 P/M thread capacity max sessions = 51, max groups = 17 path = openli-voip-example event log am.txt, uLogLevel = 8, uEventLogMode = 0x32, flush size = 1024, max size not set Event log uDebugMode = 0x0, uPktStatsLogging = 0xd, uEnableDataObjectStats = 0x1 Debuq uPrintfLevel = 5, uPrintfControl = 0 Screen output Energy saver p/m thread energy saver inactivity time = 30000 msec, sleep time = 1000 usec DSPushPackets packet cutoff alarm elapsed time not set, p/m thread preemption alarm elapsed time = 40 (msec) Alarms 00:00:00.000.721 INFO: DSConfigVoplib() voplib and codecs initialized, flags = 0x1d 00:00:00.000.749 INFO: DSConfigStreamlib() stream groups initialized 00:00:00.000.834 INFO: DSAssignPlatform() system CPU architecture supports rdtscp instruction, TSC integrity monitoring enabled 00:00.000.953 INFO: DSOpenPcap() opened pcap input file: ../pcaps/openli-voip-example.pcap 00:00:00.008.396 INFO: DSConfigMediaService() says setpriority() set Niceness to -15 for pkt/media thread 0 00:00:00.008.418 INFO: initializing packet/media thread 0, uFlags = 0x1180101, threadid = 0x7f320f34a700, total num pkt/med threads = 1 00:00:00.058.474 mediaMin INFO: SIP invite found, dst port = 43333, pyld len = 1994, len = 717, rem = 1979, start = 8, index = 0 o=02825591554 0 0 IN IP4 192.168.1.73 c=IN IP4 192.168.1.73 m=audio 5000 RTP/AVP 9 0 8 101 a=rtpmap:9 G722/8000 a=rtpmap:0 PCMU/8000 a=rtpmap:8 PCMA/8000 a=rtpmap:101 telephone-event/8000 a=extmap:1 urn:ietf:params:rtp-hdrext:csrc-audio-level a=zrtp-hash:1.10 1c812535e276bf518418c4146a20fd56e715704da9c591ae32d58ee6fed6d40f m=video 5002 RTP/AVP 96 99 a=recvonly a=rtpmap:96 H264/90000 a=fmtp:96 profile-level-id=4DE01f;packetization-mode=1 a=imageattr:96 send * recv [x=[0-1920], y=[0-1080]] a=rtpmap:99 H264/90000 **Dynamic session creation** a=fmtp:99 profile-level-id=4DE01f a=imageattr:99 send * recv [x=[0-1920], y=[0-1080]] a=zrtp-hash:1.10 c1a98e15f12937b9cad2488c6091468f7610efeefa59863c77d827669b913f38 00:00:00.058.644 INFO: DSFindDerStream() found HI interception point ID 10g-dev1, tag = 0x86, len = 8, dest port = 43332, pyld len = 1448, pyld ofs = 52 00:00:00.058.727 mediaMin INFO: Creating dynamic session 1, input #1, SDP specified codec type G711a, auto-detected bitrate 64000, stream group openli voip-example. Creation packet info: IP ver 4, ssrc = 0x14a50012, seq num = 32584, payload type 8, pkt len 200, RTP payload size 160, cat 0 00:00:00.058.781 INFO: DSCreateSession() created stream group "openli-voip-example", idx = 0, owner session = 0, status = 1

Functionality – Codecs



Multithreaded

- original 3GPP source modifications
 - instance create, delete, modify implemented using XDAIS standard
 - global data moved into per-instance "state structs"
- API interface
 - voplib shared object (.so) library, C/C++ applications include voplib.h
 - DSCodecCreate returns a codec handle, usable with DSCodecEncode and DSCodecDecode
 - also with various codec-related APIs. Some examples:
 - DSGetCodecSampleRate, DSGetCodecBitRate, DSGetCodecRawFrameSize, DSGetCodecCodedFrameSize, DSGetCodecInfo, DSGetSampleRateValue, DSGetPayloadSize, etc

Optimization

- compiler optimizations
- pragmas
- XDAIS standard requires all memory allocation done up-front, so no real-time mallocs or spin-locks

Testing

- unit / functional testing mediaTest app, with audio I/O (wav and other audio format files, USB audio)
- capacity / stress testing mediaMin app, with application packet push/pull APIs, pcap files, UDP port I/O)
- system testing using mediaMin app, highlighted in "Overview" slides
- bit-exactness testing comparison of floating-point reference vectors

Functionality – Codec API



HCODEC DSCodecCreate(void* pCodecInfo, unsigned int uFlags); /* if DS_CC_USE_TERMINFO flag is given, pCodecInfo is interpreted as TERMINATION_INFO* (shared_include/session.h), otherwise as CODEC_PARAMS* (above) */

```
void DSCodecDelete(HCODEC hCodec);
  int DSCodecEncode(HCODEC
                                  hCodec.
                  unsigned int
                                  uFlags,

    voplib.h

                  uint8 t*
                                  inData.
                  uint8 t*
                                  outData,
                  uint32 t
                                  in frameSize,

    excerpt shown here

                  CODEC OUTARGS*
                                  pOutArgs);
  int DSCodecDecode(HCODEC
                                  hCodec.
                                                                                                                    - available on Github page
                  unsigned int
                                  uFlags,
                  uint8 t*
                                  inData,
                  uint8 t*
                                  outData.
                                                                                                                    - C/C++ compatible
                  uint32 t
                                  in frameSize, /* in bytes */
                  CODEC OUTARGS*
                                  pOutArgs);
  typedef struct { /* CODEC_ENC_PARAMS */
/* generic items */
  int bitRate;
  int samplingRate;
                            /* most codecs are based on a fixed sampling rate so this is used only for advanced codecs such as EVS and Opus */
  float frameSize:
                            /* amount of data (in msec) processed by the codec per frame, for example 20 msec for AMR or EVS, 22.5 msec for MELPe, etc */
/* EVS, Opus, other advanced codec items */
  int sid_update_interval; /* interval between SID frames when DTX is enabled */
  int rf enable:
                           /* channel-aware mode (for EVS only supported at 13.2 kbps) */
  int fec indicator;
                           /* for EVS, LO = 0, HI = 1 */
                          /* for EVS, 2, 3, 5, or 7 in number of frames */
  int fec offset;
  int bandwidth limit;
                          /* for EVS, typically set to SWB or FB */
  } CODEC ENC PARAMS;
  typedef struct { /* CODEC DEC PARAMS */
/* generic items */
  int bitRate;
                            /* bitrate may not be used for codecs that can derive it from payload contents */
  int samplingRate;
                            /* not used for most codecs */
  float frameSize;
                            /* amount of data (in msec) processed by the codec per frame, for example 20 msec for AMR or EVS, 22.5 msec for MELPe, etc */
  } CODEC DEC PARAMS;
```

Functionality - Customer-Specific

- Customers often ask us to incorporate / develop specific signal processing. Some examples:
 - "deduplication" due to multiple copies of the same endpoint (with different latencies)
 - removing room echo / reverb
 - reducing background noise
- Typically a substantial impact on performance

Speech recognition (ASR)

- training is ultra sensitive to small changes in audio characteristics
- production systems are trained with wide variety of "augmentations", including background noise and babble, loud and quiet speech, frequency warping, etc.
- preprocessing to normalize speech input decreases reliance on augmentation training and increases accuracy



 major impact on performance; for real-time applications, concurrent streams may be reduced 10x

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Capacity



Performance optimized per box / VM / container

- for specified core type and clock rate, we spec a max number of concurrent streams per core. For codecs sample rate and bitrate also specified
- extensive use of htop to analyze and verify
- we observe telecom norms Signalogic has a long history of applications coded for high capacity, real-time performance

Codecs

- in addition to core type and clock rate, sample rate and bitrate must also be specified
- https://www.signalogic.com/evs_codec has a Capacity Figure table for EVS on x86

Capacity, cont.

• Extensive use of htop and to analyze / debug core usage

- hyperthreading must be disabled
- stream groups must not cross core boundaries
- look for memory leaks

htop screen capture showing

- packet/media threads
- application threads
- disabled hyperthread cores



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Capacity, cont.

Optimized for Linux

- Linux poses performance challenges not deterministic, not an RTOS
- carriers and LEAs understand "software defined solutions" are not deterministic, but still expect high capacity / reliability
- software detects and alarms "thread preemption" possible performance impairment due to Linux housekeeping and other user applications

GPUs and DPDK¹ may or may not be helpful

- GPUs
 - don't help with packet processing
 - only "matrix expressible" operations can be easily accelerated
 - can help with some codecs, but accelerating an entire codec is labor-intensive and requires hand-coding

– DPDK

- useful when combined with high-rate packet I/O hardware
- for PCIe accelerator cards, each x86 core needs a dedicated lane to avoid thread locks

Reliability and Testing



Carriers and LEAs obsess about reliability

- very long calls are common. All possible packet and audio data buffers and wrap conditions that could occur must be tested
- as with capacity, we pay attention to telecom requirements. "5 9s" up time is a minimum

Customers run stress tests for weeks at a time

- we run stress tests continuously for 6+ months
- tests include pcaps with artificial wraps, 10x packet push rates, deliberate thread preemptions, more
- tests run at max capacity ratings
- currently we run tests on Ubuntu 12.04 gcc++ 4.6.4 thru 20.04 gcc++ 9.3.0. Testing can be provided on CentOS systems as needed

Extensive use of htop and valgrind

- thorough and painstaking search for memory leaks

Software is designed for high reliability

- profiling and performance monitoring
- alarms include data flow anomalies, thread preemption
- event and packet logging
- telemetry

Audio Quality



Certain customers obsess over audio quality

 we have observed customers using metronomes and whale sounds to verify timing and frequency integrity when testing endpoints

"No sound left behind"

- we enhance audio quality by detecting and repairing:
 - packet problems (lost packets, out-of-order, gaps, bursts)
 - stream timing (overrun, underrun, child streams)

Debug capability to identify root cause (CSP, cloud, or vendor)

- audio quality is complex and subjective; ability to identify root cause is crucial



Audio Quality Challenges



Encapsulation artifacts

- encapsulation packet rate may be very different than original audio RTP packet rate - slow, fast, variable. We've seen up to ±15%
- extreme bursts of ooo (out-of-order) packets, 20-50 packets not uncommon

Streams not time-aligned

- artifacts and child streams distributed unevenly between streams
- media playout servers are particularly bad offenders



Audio Quality Verification and Debug



Test case verification

- analysis and debug tools can pinpoint whether it's CSP, cloud,or handset issue
- visual audio markers can be enabled to verify timing, frame repair, etc. Different types of markers are supported



Media Content Processing



Content analysis and signal processing

- artifact detection
- background noise reduction
- detecting and avoiding conversation overlap (correcting time alignment between streams in a stream group)
- stream deduplication

Content recognition

- speech recognition
- speaker identification
- we use Kaldi open source
- requires tradeoff between capacity and real-time processing

RTP malware detection

- malware payloads can hide in codec packets
- no way to differentiate "ordinary bad voice" from "deliberate bad voice" without extensive analysis of fully decoded packets

Current R&D

Edge Computing

- ongoing PoCs and LF Edge blueprints demonstrating hybrid cloud, enhanced privacy / security
- many telecom carriers do not trust security in public clouds

ASR (Automatic Speech Recognition)

- can be done in real-time, but substantially less capacity
- not yet in real-time: individual speaker identification and transcription, known as "diarization"
- potential to reduce workloads, accurately alert on "conversations of interest"
- open source accuracy only a few % WER² more than proprietary code bases

Telecom migration to public cloud

- containerized solutions needed
- LI is a particular problem due to encryption requirements
- allow CICD¹, for example improving ASR accuracy with "on the fly" training based on collected data

¹ Continuous Integration, Continuous Deployment ² WER = Word Error Rate

Edge Computing + Containerization



Challenges

Varying latencies between endpoints Background noise Overlapping conversations Avoid using GPUs when possible Signalogic.

ASR Basics

Deep Learning Architecture

- combines previous generation xMM¹ technology with DNNs (Deep Neural Networks)
- relies on extensive training and "augmentation" methods
- Kaldi open source is basis for Alexa, Google Home, and Cortana

Frequency domain "images"

- formed by sliding FFT analysis of incoming time series data. Each FFT frame output is similar to cochlea in human ears
- groups of FFT frames form images
- successive images are called "TDNN" (time delayed DNN), similar to series of CNNs²





Prepared by Signalogic for Akraino Technical Meeting 1Q22

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Containers and Kubernetes



Packet + media + ASR inside container

- minimum 2 x86 cores, 32 GB mem, 1 TB HDD can handle 32 sessions
- a session is wideband decode (e.g. EVS), jitter buffer, stream merging up to 8 stream groups, G711 pcap output, wideband wav file output
- scales up linearly with more cores

Field apps



LI Perspective

- ETSI LI Terminology: CC mediation (communication content), HI2 and HI3 (Handover Interfaces)
- Packet Handling
 - Jitter buffer, packet repair, rate adjustment
- Media •
 - Decoding (AMR, AMR-WB, EVS, more), stream alignment

Signal Processing •

- Stream merging, conferencing, speech recognition



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RAINO